## Laplacian And Harmonic Forms

• In this section, let (M, g) be an oriented Riemannian manifold, compact and without boundary. We note, however, that compactness is needed only when the formula (1) below

is used.

- We defined the inner product  $\langle \omega_p, \eta_p \rangle$  at each point for two k-forms on M.
- We now introduce the inner product in  $\mathcal{A}^k(M)$  by integrating the function  $\langle \omega_p, \eta_p \rangle$  over M; i.e.

(1) 
$$(\omega,\eta) = \int_M \langle \omega,\eta \rangle \, v_M,$$

where  $v_M$  is the volume element of M. The following properties hold:

- (i) (linearity)  $(a\omega + b\omega', \eta) = a(\omega, \eta) + b(\omega', \eta).$
- (ii) (symmetry)  $(\omega, \eta) = (\eta, \omega).$
- (iii) (positive-definite)  $(\omega, \omega) \ge 0$ ;  $(\omega, \omega) = 0$  iff  $\omega = 0$ .
- Thus  $(\cdot, \cdot)$  is an inner product on the vector space  $\mathcal{A}^k(M)$ .

In particular, the length  $\|\omega\| = \sqrt{(\omega, \omega)}$  is defined.

• The inner product (1) can also be written in the form

(2) 
$$(\omega,\eta) = \int_M \omega \wedge *\eta = \int_M \eta \wedge *\omega.$$

We have also

$$(*\omega,*\eta) = (\omega,\eta),$$

which means that the Hodge operator  $* : \mathcal{A}^k(M) \to \mathcal{A}^{n-k}(M)$  is isometric relative to the inner product above.

 By convention, we define the inner product between differential forms of two different degrees to be 0,

so that the entire space  $\mathcal{A}^*(M)$  is provided with an inner product.

- Next we study how exterior differentiation  $d : \mathcal{A}^*(M) \to \mathcal{A}^*(M)$  is transformed by the Hodge operator.
- For this purpose, we consider linear operator

$$\delta^{k-1} = (-1)^k *^{-1} d* = (-1)^{n(k-1)+1} * d*$$

by requiring the following diagram be commutative

$$\begin{array}{cccc} \mathcal{A}^{k}(M) & \stackrel{*}{\longrightarrow} & \mathcal{A}^{n-k}(M) \\ \delta & & & \downarrow d \\ \mathcal{A}^{k-1}(M) & \stackrel{}{\xrightarrow{(-1)^{k}*}} & \mathcal{A}^{n-k+1}(M). \end{array}$$

From the definition, we immediately see that

$$*\delta = (-1)^k d*, \ \delta * = (-1)^{k^2 + 1} * d, \ \delta \circ \delta = 0.$$

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**Proposition 1.** Relative to the inner product  $(\cdot, \cdot)$  in  $\mathcal{A}^*(M)$ ,  $\delta$  is an adjoint operator of exterior differentiation d; o.e., we have

(3) 
$$(d\omega, \eta) = (\omega, \delta\eta).$$

Conversely, d is an adjoint operator of  $\delta$ .

*Proof.* It suffices to prove (3) when  $\omega$  and  $\eta$  are k- and (k + 1)- forms, respectively. In this case, we have

$$d\omega \wedge *\eta = d(\omega \wedge *\eta) - (-1)^k \omega \wedge d * \eta$$
$$= d(\omega \wedge *\eta) + \omega \wedge *\delta\eta.$$

Integrating each side over M, we obtain from (2)

$$(d\omega,\eta) = \int_M d(\omega \wedge *\eta) + (\omega,\delta\eta) = (\omega,\delta\eta).$$

**Definition.** For a Riemannian manifold M, the operator defined by

$$\Delta = d\delta + \delta d : \mathcal{A}^k(M) \to \mathcal{A}^k(M)$$

is called the Laplacian or Laplace-Beltrami operator.

• A form  $\omega \in \mathcal{A}^*(M)$  such that  $\Delta \omega = 0$  is called a harmonic form. In particular, a function such that  $\Delta f = 0$  is called a harmonic function.

**Example.** To compute the Laplacian on  $\mathbb{R}^n$ , it suffices to compute  $\Delta \omega$  for a k-form written

$$\omega = f \, dx_{i_1} \wedge \dots \wedge dx_{i_k},$$

where  $x_1, \dots, x_n$  are the ordinary coordinates in  $\mathbb{R}^n$ . - First, choose  $j_1, \dots, j_{n-k}$  such that

$$dx_{i_1} \wedge \dots \wedge dx_{i_k} \wedge dx_{j_1} \wedge \dots \wedge dx_{j_{n-k}} = dx_1 \wedge \dots \wedge dx_n.$$

Then we obtain, by the definition of \*,

$$*\omega = f \, dx_{j_1} \wedge \dots \wedge dx_{j_{n-k}}$$

$$d * \omega = \sum_{s=1}^{k} \frac{\partial f}{\partial x_{i_s}} dx_{i_s} \wedge dx_{j_1} \wedge \dots \wedge dx_{j_{n-k}},$$

$$\delta\omega = (-1)^{n(k+1)+1} * d * \omega = \sum_{s=1}^{k} \frac{\partial f}{\partial x_{i_s}} dx_{i_s} \wedge dx_{i_1} \wedge \cdots \widehat{dx_{i_s}} \wedge \cdots \wedge dx_{i_k}.$$

Therefor we obtain

(4) 
$$d\delta\omega = -\sum_{s=1}^{k} \frac{\partial^{f}}{\partial x_{i_{s}}^{2}} dx_{i_{s}} \wedge dx_{i_{1}} \wedge \dots \wedge dx_{i_{k}} + (-1)^{s} \frac{\partial^{2} f}{\partial x_{i_{s}} \partial x_{j_{t}}} dx_{j_{t}} \wedge dx_{i_{s}} \wedge dx_{i_{1}} \wedge \dots \widehat{dx_{i_{s}}} \wedge \dots \wedge dx_{i_{k}}$$

— On the other hand, we have

$$d\omega = \sum_{s=1}^{n-k} \frac{\partial f}{\partial x_{j_s}} dx_{j_s} \wedge dx_{j_s} \wedge dx_{i_1} \wedge \dots \wedge dx_{i_k},$$

and thus

$$*d\omega = \sum_{s=1}^{n-k} (-1)^{k+s-1} \frac{\partial f}{\partial x_{j_s}} dx_{j_1} \wedge \widehat{dx_{j_s}} \wedge \dots \wedge dx_{j_{n-k}}$$

Further, we have

$$d * d\omega = \sum_{s=1}^{n-k} (-1)^k \frac{\partial^2 f}{\partial x_{x_{j_s}}^2} dx_{j_1} \cdots \wedge dx_{j_{n-k}}$$
$$+ \sum_{s=1}^{n-k} \sum_{t=1}^k (-1)^{k+s-1} \frac{\partial^2 f}{\partial x_{j_s} \partial x_{i_s}} dx_{i_s} \wedge dx_{j_1} \wedge \widehat{dx_{j_s}} \wedge \cdots \wedge dx_{j_{n-k}},$$

and hence

(5) 
$$\delta d\omega = -\sum_{s=1}^{n-k} \frac{\partial^2 f}{\partial x_{x_{j_s}}^2} dx_{i_1} \cdots \wedge dx_{i_k} + \sum_{s=1}^{n-k} \sum_{t=1}^k (-1)^{t+1} \frac{\partial^2 f}{\partial x_{j_s} \partial x_{i_s}} dx_{j_s} \wedge dx_{i_1} \wedge \widehat{dx_{i_t}} \wedge \cdots \wedge dx_{i_k}.$$

— Adding (4) and (5), we arrive at

$$\Delta \omega = -\sum_{s=1}^{n-k} \frac{\partial^2 f}{\partial x_{x_{j_s}}^2} dx_{i_1} \cdots \wedge dx_{i_k}.$$

Thus the Laplacian is an extension of the classical Laplace operator to the case of a general Riemannian manifold.

**Proposition 2.** The Laplacian  $\Delta$  has the following properties:

(i)  $*\Delta = \Delta *$ . If  $\omega$  is a harmonic form, so is  $*\omega$ .

(ii)  $\Delta$  is self-adjoint, that is,

$$(\Delta\omega,\eta) = (\omega,\Delta\eta), \quad \forall \omega,\eta \in \mathcal{A}^*(M).$$

(iii)  $\Delta \omega = 0$  iff  $d\omega = 0$  and  $\delta \omega = 0$ .

*Proof.* (i) is simple.

(ii) follows from the fact that d and  $\delta$  are adjoint to each other.

(iii) ( $\Leftarrow$ ) If  $d\omega = \delta \omega = 0$ , then clearly  $\Delta \omega = 0$ .

 $(\Rightarrow)$  To show the converse, we need the assumption that M is compact. In this case, the equality

$$0 = (\Delta\omega, \omega) = ((d\delta + \delta d)\omega, \omega) = (\delta\omega, \delta\omega) + (d\omega, d\omega) = 0$$

shows that  $\Delta \omega = 0$  implies  $\|\delta \omega\| = \|d\omega\| = 0$ , i.e.,  $d\omega = \delta \omega = 0$ .  $\Box$ 

**Corollary 3.** If (M, g) is a connected, oriented **compact** Riemannian *n*-manifold,

then (i) a harmonic function on M is a constant function, and

(ii) a harmonic *n*-form is a constant multiple of the volume element  $dv_g$ .

*Proof.* (i) If a function f satisfies  $\Delta f = 0$ , then Proposition 2(iii) implies df = 0. Hence f is a constant function if M is connected.

(ii) Any n-form on M must be a function times the volume element:

$$\omega = f \, dv_g$$

If  $\Delta \omega = 0$ , then

$$*\omega = *(f \, dv_g) = f$$

is a harmonic function, hence f = constant c; i.e.  $\omega = c \, dv_g$ .  $\Box$ 

- Let M be an oriented **compact** Riemannian manifold.
- If r is the number of connected components, then both  $H^0_{dB}(M)$  and  $H^n_{dB}(M)$  are isomorphic to the derect sum of r copies of  $\mathbb{R}$ .
- From Corollary 3, it follows that for k = 0 and for k = n, every element of  $H_{dR}^k$  is represented by a uniquely determined harmonic form.
- This fact remains valid for every k, as we will see in the Hodge theorem.